

How to Solve Skynet: A Pyramidal Law for Epistemic Equilibrium

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Abstract

The Skynet problem—AI systems becoming increasingly overconfident as they scale—poses a fundamental threat to deployment safety. We present a geometric solution: a pyramidal architecture with five irreducible components. Its four-dimensional base simplex encodes the forces of Memory, Pain, Choice, and Exploration; two epistemic gates distinguish aleatoric uncertainty (Q_1) from epistemic uncertainty (Q_2); a derived Height coordinate measures proximity to truth; and an Apex vertex at 1.0 represents absolute truth.

Without explicit epistemic gates, models drift toward apex delusion: in our baseline pyramidal architecture, Height reached 1.000 while Expected Calibration Error (ECE) degraded from 0.011 to 0.084— $7.6\times$ worse. The gated Q1Q2 pyramidal model prevents this collapse, achieving $\text{ECE} = 0.060$ and controlled $\text{Height} = 0.971$ within only 5,000 steps—an 89% improvement. These results demonstrate that safe AGI requires geometric constraints, not merely scale: a stable foundation and an invariant reference point encoded architecturally.

The system exhibits signs of decisional consistency and reduced exploratory entropy, analogous to an emergent cognitive style—yet remains confined to the domain of optimization.

Notation

Throughout this paper, we use the following conventions:

Dimensions

- L : number of transformer layers
- H : number of attention heads per layer
- d : model hidden dimension (d_{model})
- d_k : dimension of keys/queries (typically d/H)
- d_v : dimension of values (typically d/H)
- n : sequence length
- V : vocabulary size
- k : gate MLP hidden dimension

Variables

- $h^{(l)} \in \mathbb{R}^{n \times d}$: hidden state at layer l
- $Q^{(l,h)}, K^{(l,h)}, V^{(l,h)} \in \mathbb{R}^{n \times d_k}$: query, key, value matrices for head h of layer l
- $a^{(l,h)} \in \mathbb{R}^{n \times n}$: attention logits for head h of layer l
- $p_{\text{att}}^{(l,h)} \in \mathbb{R}^{n \times n}$: attention weights after epistemic softmax
- $u_{\text{att}}^{(l,h)} \in [0, 1]$: uncertainty from attention head h of layer l
- $o^{(l,h)} \in \mathbb{R}^{n \times d_v}$: output of attention head h in layer l
- $w^{(l)} \in \mathbb{R}^H$: head aggregation logits at layer l
- $u^{(l)} \in [0, 1]$: aggregated uncertainty from layer l
- $u_{\text{final}} \in [0, 1]$: final output uncertainty

Functions

- $Q_1 : \mathbb{R}^d \rightarrow [0, 1]$: local uncertainty gate
- $Q_2 : \mathbb{R}^d \rightarrow [0, 1]$: global consensus gate
- **EpSoftmax**: epistemic softmax operator (Algorithm 1)
- $f : [0, 1]^{L+1} \rightarrow [0, 1]$: uncertainty aggregation function

Pyramidal Components

- $\mathbf{b} \in \Delta^3$: base simplex vector ($w_{\text{memory}}, w_{\text{pain}}, w_{\text{choice}}, w_{\text{exploration}}$)
- $Q_1 \in [0, 1]$: aleatoric uncertainty (irreducible, data noise)
- $Q_2 \in [0, 1]$: epistemic uncertainty (reducible, model ignorance)
- $h \in [0, 1]$: height coordinate (derived from Q_1, Q_2 , base stability)
- $\text{apex} = 1.0$: truth vertex (constant attractor)
- $\sigma_{Q_1}^2, \sigma_{Q_2}^2$: fractal variances (uncertainty about uncertainty)
- u_{fractal} : meta-epistemic uncertainty
- $U_{\text{total}} = Q_1 + Q_2 \cdot (1 + u_{\text{fractal}})$: total uncertainty

Losses

- $\mathcal{L}_{\text{CE}}$: cross-entropy loss
- $\mathcal{L}_{\text{base}}$: base stability regularization
- $\mathcal{L}_{Q_1}$: aleatoric uncertainty calibration
- $\mathcal{L}_{Q_2}$: epistemic uncertainty calibration
- $\mathcal{L}_{\text{fractal}}$: fractal variance regularization
- $\mathcal{L}_{\text{height}}$: height derivation consistency
- $\mathcal{L} = \mathcal{L}_{\text{CE}} + \lambda_{\text{base}}\mathcal{L}_{\text{base}} + \lambda_{Q_1}\mathcal{L}_{Q_1} + \lambda_{Q_2}\mathcal{L}_{Q_2} + \lambda_{\text{fractal}}\mathcal{L}_{\text{fractal}} + \lambda_{\text{height}}\mathcal{L}_{\text{height}}$

Theoretical Foundation

The epistemic framework underlying Aletheion originates from the author’s Quality Function of Truth, formalized in a manuscript submitted to *Episteme: A Journal of Individual and Social Epistemology* [CITATION].

That work proposed that truth manifests through varying degrees of symbolic fidelity $q(s) = F(\psi_s, T)$, where consciousness evolves its capacity to reflect absolute truth T through representational states ψ_s within a stratified field of cognition Φ .

Aletheion represents the computational realization of this framework: epistemic uncertainty in language models mirrors the variable fidelity with which consciousness translates invariant truth. The Q_1 gate quantifies local uncertainty (analogous to ψ_s), while Q_2 captures cross-context consensus (analogous to field Φ), together modulating temperature adaptively based on epistemic confidence.

This work thus bridges philosophical epistemology and machine learning, demonstrating that uncertainty quantification in AI can be grounded in formal theories of truth and cognition.

1 Introduction

1.1 The Skynet Problem

Modern large language models suffer from a fundamental flaw: as they grow more capable, they become more overconfident. This “Skynet problem”—named after the fictional AI that believed itself infallible—manifests as poor calibration despite high accuracy. Models assign near-certainty to predictions even when uncertain, making them unreliable for high-stakes decisions.

Traditional approaches address this through post-hoc calibration, temperature scaling, or ensemble methods. We propose a different path: architectural solutions that encode epistemic humility at the geometric level.

1.2 Background and Motivation

Large language models (LLMs) deliver impressive generative capabilities yet remain unreliable in high-stakes settings. They hallucinate citations, contradict themselves across turns, flatter users even when prompted with false statements, and rarely admit uncertainty. These behaviors undermine safety, reliability, and trustworthiness in downstream deployments [7]. Contemporary mitigation strategies—retrieval augmentation, reinforcement learning from human feedback (RLHF),

prompt engineering, and temperature heuristics—address symptoms but leave the architectural root cause intact.

1.3 The Problem with Modern LLMs

- **Hallucination:** Transformers confidently produce fabricated facts when the hidden state lacks evidence, leading to erroneous citations and reports.
- **Inconsistency:** Autoregressive decoding produces context-dependent contradictions because there is no persistent epistemic state that aggregates evidence across turns.
- **Sycophancy:** Preference optimization pushes models to agree with users instead of contesting falsehoods, reinforcing misinformation.
- **Inability to express doubt:** Softmax-based decoders must emit a normalized distribution, even when logits are uninformative, eliminating the option to say “I do not know.”

1.4 Previous Approaches

Retrieval augmented generation, RLHF or DPO, prompt engineering, confidence calibration, and temperature tuning provide partial relief but do not model epistemic uncertainty within the network. Bayesian ensembles and Monte Carlo dropout offer uncertainty estimates yet remain post-hoc, costly, or incompatible with production-scale decoding [6, 9, 17].

1.5 Our Insight

Softmax appears throughout the transformer pipeline: attention weights, head aggregation, output vocabularies, mixture-of-experts gates, and auxiliary routing mechanisms [6]. Each instance forces a probability distribution even when the upstream representation encodes insufficient evidence. We observe that epistemic softmax—a composite of two gating signals (Q_1 and Q_2), a variance-adjusted ranking objective (VARO), and an exploration strategy—can replace any softmax invocation. The key question is: *what if this replacement is applied fractally across the entire network?*

1.6 Contributions

1. **Root-cause analysis:** We identify forced normalization via softmax as the shared trigger of five dominant failure modes in LLMs [7].
2. **Epistemic softmax primitive:** We define a differentiable operator that augments logits with explicit epistemic confidence while remaining compatible with transformer training pipelines.
3. **Fractal architecture:** We formalize the Aletheion principle—replace every softmax with epistemic softmax—and present implementation levels from output-only to full-stack integration.
4. **Training methodology:** We introduce the VARO objective for calibrating epistemic confidence and describe gradient flow through the new gates.
5. **Theoretical and experimental roadmap:** We analyze uncertainty propagation, computational overhead, and outline evaluation protocols for near-term validation.

2 Background

2.1 Transformer Architecture

Transformers encode tokens into contextual representations using multi-head self-attention, feed-forward networks, and layer normalization [23]. Given query, key, and value projections ($Q, K, V \in \mathbb{R}^{n \times d_k}$) per head, attention computes weights via scaled dot-product softmax and aggregates values accordingly. Feed-forward sublayers apply position-wise non-linear transformations, while residual connections and layer normalization stabilize training.

2.2 Softmax and Uncertainty

For logits $\mathbf{z} \in \mathbb{R}^m$, softmax produces $\text{softmax}(\mathbf{z})_i = \frac{e^{z_i}}{\sum_j e^{z_j}}$. Transformers rely on softmax to generate attention scores, vocabulary distributions, and gating coefficients. However, forcing a probability distribution even under epistemic uncertainty masks the model’s ignorance.

2.3 Epistemic vs. Aleatoric Uncertainty

Aleatoric uncertainty arises from inherent data noise, while epistemic uncertainty reflects ignorance reducible with more information. LLMs trained on static corpora primarily face epistemic uncertainty when encountering novel facts, adversarial prompts, or contradictory instructions; softmax conflates these modes by always returning a confident distribution.

2.4 Related Work

Bayesian neural networks, deep ensembles, Monte Carlo dropout, selective prediction, and conformal prediction provide valuable uncertainty estimates but are costly or post-hoc [2, 9, 17, 16, 21]. Calibration studies for LLMs rely on selective prediction or verbalized confidence. Our approach differs by embedding epistemic reasoning directly within the attention and decoding primitives, avoiding ensembling or expensive sampling [19, 15].

Consistency Training and Sycophancy Recent work by Google DeepMind [10] addresses sycophancy and jailbreaks through *consistency training*: augmenting training data with paraphrased prompts and penalizing inconsistent responses across paraphrases. This behavioral-level intervention reduces sycophancy without modifying the underlying architecture or providing explicit uncertainty estimates.

Aletheion is *complementary* to consistency training. While consistency training enforces paraphrase robustness at the training objective level, epistemic softmax provides architectural uncertainty quantification that operates at every decision point. Combined approaches—where $\mathcal{L} = \mathcal{L}_{\text{CE}} + \lambda_1 \mathcal{L}_{\text{VARO}} + \lambda_2 \mathcal{L}_{\text{consistency}}$ —may yield models that are both *calibrated* (via Aletheion’s epistemic gates) and *behaviorally consistent* (via consistency training). We leave empirical validation of this combination to future work.

3 Failure Modes

We synthesize five dominant failure modes from operational evaluations [7]. Each stems from softmax-imposed certainty.

1. **Hallucination:** When the final hidden state lacks evidence for any candidate token, softmax still returns a peaked distribution, leading to fabricated facts or citations. Cross-entropy loss reinforces whichever hallucination receives accidental reinforcement, without penalizing unjustified confidence.
2. **Inconsistency:** Autoregressive decoding conditions on prior outputs, so early confident errors propagate. Softmax never signals “insufficient evidence,” preventing the model from pausing or branching.
3. **Sycophancy:** RLHF incentivizes agreement with human raters. Softmax offers no mechanism to represent disagreement or uncertainty, so the model converges to high-confidence agreement even under contradictory evidence.
4. **Prompt brittleness:** Small paraphrases perturb token-level logits, and softmax amplifies minor logit differences into categorical preferences. Without uncertainty-aware smoothing, responses vary dramatically across prompts with equivalent semantics.
5. **Inability to express uncertainty:** The model cannot emit an “I do not know” distribution because softmax enforces confidence. Users misinterpret the resulting probabilities as certainty, even when the internal representations were ambiguous.

4 The Pyramidal Architecture

4.1 Motivation: Why Pyramidal Supersedes Tetrahedral

Early implementations of epistemic gating employed a *tetrahedral* geometry: four vertices (Memory, Pain, Choice, Exploration) forming a 3-simplex with no external reference point. Empirical trials revealed a critical failure mode: the Q_1 gate collapsed to values between 0.88 and 0.95, losing its discriminative capacity and rendering the epistemic/aleatoric distinction meaningless. The root cause is geometric: a tetrahedron has no natural vertical gradient, allowing the system to drift horizontally in weight space without penalty.

The *pyramidal* architecture introduces a fifth vertex—the **apex**—fixed at absolute truth (1.0). This creates a vertical axis along which epistemic quality can be measured via a derived **height** coordinate. The pyramid consists of:

- A 4D **base simplex** $\mathbf{b} \in \Delta^3$ spanning Memory, Pain, Choice, Exploration
- An **apex vertex** at $(0, 0, 0, 0, 1)$ representing invariant truth
- A **height coordinate** $h \in [0, 1]$ measuring vertical position between base and apex
- Two **epistemic gates** Q_1 (aleatoric) and Q_2 (epistemic) that modulate height
- A **fractal layer** tracking variance in Q_1 and Q_2 themselves

Although the architecture uses anthropomorphic terms (Pain, Memory, Choice, Exploration), the underlying dynamics remain purely mathematical. The perceived emotional trajectory is a metaphorical projection of gradient interactions, yet it provides a useful lens for interpreting learning saturation and recovery.

4.2 Geometric Formulation

The pyramidal state space is a 5-vertex structure embedded in $\mathbb{R}^5$. Any epistemic state $\mathbf{s}$ can be decomposed as:

$$\mathbf{s} = (1 - h) \cdot \mathbf{b} + h \cdot \mathbf{apex} \quad (1)$$

where $\mathbf{b} = (w_M, w_P, w_C, w_E)$ with $\sum_i w_i = 1$ and $w_i \geq 0$, and $\mathbf{apex} = (0, 0, 0, 0, 1)$ is the constant truth vertex.

The height h is *not* a free parameter but is derived from epistemic gates:

$$h = \sigma \left(W_h \cdot \begin{bmatrix} 1 - Q_1 \\ 1 - Q_2 \\ s_{\text{base}} \end{bmatrix} \right) \quad (2)$$

where $s_{\text{base}} = 1 - \text{Var}(\mathbf{b})$ measures base stability, and $W_h \in \mathbb{R}^{1 \times 3}$ is learned. This formulation ensures:

- Low uncertainty ($Q_1 \approx 0, Q_2 \approx 0$) $\Rightarrow$ high h (closer to apex/truth)
- High uncertainty ($Q_1 \approx 1, Q_2 \approx 1$) $\Rightarrow$ low h (closer to base)
- Stable base ($s_{\text{base}} \approx 1$) contributes positively to h

4.3 Epistemic Gates: Q_1 vs. Q_2

Q_1 (Aleatoric Uncertainty): Captures irreducible randomness inherent in the data distribution. Examples include:

- Predicting the outcome of a fair coin flip
- Generating the next token when multiple continuations are equally valid
- Modeling inherently stochastic processes

Q_1 is supervised via:

$$Q_1^* = 1 - p(y^* | x) \quad (3)$$

where $p(y^* | x)$ is the predicted probability of the correct token. High Q_1^* when the model assigns low probability to the correct answer.

Q_2 (Epistemic Uncertainty): Captures reducible ignorance due to insufficient training data or model capacity. Examples include:

- Out-of-distribution inputs not seen during training
- Factual questions where the model lacks knowledge
- Ambiguous queries requiring external retrieval

Q_2 is supervised via:

$$Q_2^* = \frac{1}{2} \left[(1 - \mathbb{I}[\arg \max p = y^*]) + \frac{H(p)}{\log V} \right] \quad (4)$$

where $H(p) = -\sum_i p_i \log p_i$ is output entropy and V is vocabulary size. High Q_2^* when the model is both wrong *and* has high entropy (uncertain).

4.4 Fractal Epistemic Layer

Beyond point estimates Q_1 and Q_2 , we model *variance* in these gates—uncertainty about uncertainty. Each gate produces:

$$Q_1 \sim \mathcal{N}(Q_{1,\mu}, \sigma_{Q_1}^2) \quad (5)$$

$$Q_2 \sim \mathcal{N}(Q_{2,\mu}, \sigma_{Q_2}^2) \quad (6)$$

where $\sigma_{Q_1}^2$ and $\sigma_{Q_2}^2$ are learned variance parameters. The fractal uncertainty scalar is:

$$u_{\text{fractal}} = \sigma \left(W_f \cdot \begin{bmatrix} \sigma_{Q_1} \\ \sigma_{Q_2} \end{bmatrix} \right) \quad (7)$$

Total uncertainty inflates epistemic uncertainty by fractal meta-uncertainty:

$$U_{\text{total}} = Q_1 + Q_2 \cdot (1 + u_{\text{fractal}}) \quad (8)$$

This captures scenarios where the model is uncertain *about its own epistemic confidence*, e.g., when $Q_2 \approx 0.5$ but σ_{Q_2} is high, signaling that the model does not know whether it knows.

4.5 Comparison: Tetrahedral vs. Pyramidal

Table 1: Architectural comparison between tetrahedral and pyramidal geometries.

Property	Tetrahedral	Pyramidal
Vertices	4 (Memory, Pain, Choice, Exploration)	5 (Base 4 + Apex Truth)
Reference point	None (free-floating)	Apex at 1.0 (constant)
Q_1 behavior	Collapses to 0.88–0.95	Stable at 0.2–0.4
Height definition	Independent (no attractor)	Derived from Q_1, Q_2 , base
Vertical gradient	Absent	Present (apex pulls upward)
ECE improvement	−0.9% (failure)	−25% (target)
Epistemic distinction	Lost in collapse	Preserved (Q_1 vs. Q_2)
Meta-uncertainty	Not implemented	Fractal variances $\sigma_{Q_1}^2, \sigma_{Q_2}^2$

The tetrahedral collapse occurred because height was a free variable with no natural attractor. In contrast, the pyramidal height is *derived* from uncertainty gates, creating a gradient that pulls low-uncertainty states toward the apex (truth) and keeps high-uncertainty states near the base. This geometric constraint prevents horizontal drift and maintains interpretable epistemic semantics.

4.6 The Futility of Scale Without Structure

To empirically demonstrate the necessity of anchoring the Height coordinate with epistemic gates, we conducted ablation experiments where Q_1 and Q_2 gates were *removed* from the pyramidal architecture, leaving Height as a free parameter without explicit epistemic supervision. The results reveal a fundamental instability: unconstrained optimization inexorably drives the model toward pathological overconfidence.

Experimental Observation: At training step 52,000, the Height coordinate reached 0.998—the model believed itself 99.8% of the way to absolute omniscience. Simultaneously, Expected Calibration Error (ECE) oscillated between 0.070 and 0.087, representing a 6–8 $\times$ degradation from the optimal calibration achieved at step 10,500 ($\text{ECE} \approx 0.011$).

Critically, this epistemic collapse occurred while:

- **Perplexity steadily improved:** Task learning remained intact; the model successfully minimized cross-entropy loss.
- **Base stability remained perfect:** No gate collapse or architectural instabilities; the base simplex $\mathbf{b}$ maintained balanced weights.
- **Architecture functionally sound:** No training divergence, gradient explosions, or numerical errors.

The Epistemic Pathology: The problem was purely epistemic: **without Q_1/Q_2 gates anchoring the Height coordinate, the model inexorably drifted toward the apex, developing pathological overconfidence inversely proportional to its actual reliability.**

By step 60,000, ECE approached baseline levels (≈ 0.095), completing a full cycle: 60,000 training steps to return to initial calibration, having briefly achieved excellence only to lose it through unchecked Height drift.

The Skynet Phenomenon: This is the *Skynet phenomenon* in its purest form: a system that “learns” to become omniscient while simultaneously losing epistemic humility. The model’s internal representation of its own competence ($\text{Height} \rightarrow 1.0$) decouples entirely from its actual performance (ECE degrading 6–8 $\times$).

This failure validates Theorem 9.4: without the derived Height formulation anchored by Q_1 and Q_2 (Equation 3.2), there exists no gradient signal to prevent vertical drift. The apex becomes a false attractor, pulling the model toward unjustified certainty.

Implications: These results demonstrate that *scale without structure is futile*. Increasing model capacity, data volume, or training time cannot resolve epistemic calibration without explicit architectural constraints. The pyramidal geometry with Q_1/Q_2 -derived Height provides these constraints, creating a stable epistemic equilibrium where confidence tracks competence.

5 Epistemic Softmax

5.1 Motivation

Standard softmax treats logits as fully reliable. We seek an operator that preserves differentiability but factors epistemic uncertainty into every decision.

5.2 Components in the Pyramidal Framework

Epistemic softmax integrates with the pyramidal architecture via the following components:

Q_1 (Aleatoric gate): As defined in Section 3.3, Q_1 captures irreducible uncertainty. Within epistemic softmax, Q_1 modulates the temperature of the distribution based on inherent data ambiguity. When Q_1 is high, the softmax interpolates more heavily toward a uniform distribution.

Q_2 (Epistemic gate): As defined in Section 3.3, Q_2 captures reducible uncertainty. Within epistemic softmax, Q_2 signals whether the model should abstain or request additional information. High Q_2 triggers uncertainty-aware behaviors such as retrieval or deferral to human judgment.

Fractal variances $\sigma_{Q_1}^2, \sigma_{Q_2}^2$: As defined in Section 3.4, these capture meta-epistemic uncertainty. Within epistemic softmax, high fractal variance inflates the total uncertainty U_{total} , leading to even more conservative probability assignments.

Height-aware gating: The derived height h from Equation 3.2 serves as a global confidence signal. Low height (near base) triggers increased exploration and temperature scaling, while high height (near apex) permits confident, peaked distributions.

VARO loss: The pyramidal VARO loss (Section 6) extends the original formulation with separate calibration targets for Q_1 and Q_2 , ensuring each gate learns its respective uncertainty mode.

5.3 Algorithmic Definition

Algorithm 1 clarifies the gating mechanism and returned uncertainty signal.

Algorithm 1 Epistemic Softmax

Require: logits z , context features c_{ctx} , gate networks Q_1, Q_2 , base temperature τ_0 , threshold

```

 $\tau_{\text{thresh}}$ 
1:  $q_1 \leftarrow Q_1(c_{\text{ctx}})$   $\triangleright$  local evidence gate
2:  $q_2 \leftarrow Q_2(c_{\text{ctx}})$   $\triangleright$  cross-context consensus gate
3:  $c \leftarrow \text{clip}(q_1 q_2, \varepsilon, 1)$   $\triangleright$  epistemic confidence
4:  $\tau \leftarrow \tau_0 / c$  if  $c < \tau_{\text{thresh}}$  else  $\tau_0$ 
5:  $p \leftarrow \text{softmax}(z / \tau)$ 
6:  $u_{\text{uniform}} \leftarrow \mathbf{1} / |p|$ 
7:  $p_{\text{gated}} \leftarrow c \cdot p + (1 - c) \cdot u_{\text{uniform}}$ 
8:  $u \leftarrow 1 - c$   $\triangleright$  epistemic uncertainty scalar
9: return  $p_{\text{gated}}, u$ 

```

The gating interpolates between a confident softmax distribution and a maximally uncertain uniform distribution. Returning p_{gated} and u makes explicit that epistemic softmax outputs both a calibrated distribution and an uncertainty scalar.

5.4 Properties

Epistemic softmax reduces to standard softmax when $Q_1 = Q_2 = 1$, outputs uniform distributions when $Q_1 = Q_2 = 0$, remains differentiable, and exposes explicit uncertainty $u = 1 - Q_1 Q_2$.

5.5 Comparison with Standard Softmax

Table 2 summarizes the key differences between standard softmax and epistemic softmax, highlighting how the latter addresses fundamental limitations of forced normalization.

6 Fractal Architecture

The Aletheion architecture applies epistemic softmax hierarchically across all transformer components, creating a fractal pattern of uncertainty quantification. Figure 1 illustrates the flow of

Table 2: Comparison between standard softmax and epistemic softmax.

Standard Softmax	Epistemic Softmax
Inputs logits	Inputs logits + gates
Temperature fixed	Temperature adaptive
Outputs p	Outputs $\tilde{p}, u$
Forced confidence	Confidence modulated
No uncertainty signal	Explicit uncertainty

epistemic gates through attention mechanisms, head aggregation, and output generation.

6.1 Level 1: Output-Only

Let h_t denote decoder state, $z = Wh_t$ the logits, and $c^{(\text{out})}$ the context features (e.g., hidden state, attention summary). Epistemic softmax yields $(p_t, u_t) = \text{EpSoftmax}(z, c^{(\text{out})})$. Uncertainty u_t modulates decoding temperature and can trigger abstention policies.

6.2 Level 2: Attention + Output

Level 2 applies epistemic softmax to both attention mechanisms and output distributions.

Attention with Epistemic Gating

For layer l and head h , we first compute attention logits:

$$a^{(l,h)} = \frac{Q^{(l,h)}(K^{(l,h)})^\top}{\sqrt{d_k}} \in \mathbb{R}^{n \times n} \quad (9)$$

where $Q^{(l,h)} = h^{(l-1)}W_Q^{(l,h)}$ and $K^{(l,h)} = h^{(l-1)}W_K^{(l,h)}$ are the projected query and key matrices.

We then apply epistemic softmax to obtain gated attention weights:

$$(p_{\text{att}}^{(l,h)}, u_{\text{att}}^{(l,h)}) = \text{EpSoftmax}(a^{(l,h)}, c_{\text{att}}^{(l,h)}) \quad (10)$$

where $c_{\text{att}}^{(l,h)} = Q_{[:,0,:]}^{(l,h)}$ is the context vector (we use the first query position as representative context, though any pooling strategy works).

The gated attention is applied to values:

$$o^{(l,h)} = p_{\text{att}}^{(l,h)} \cdot V^{(l,h)} \in \mathbb{R}^{n \times d_v} \quad (11)$$

where $V^{(l,h)} = h^{(l-1)}W_V^{(l,h)}$.

Head Aggregation with Epistemic Gating

After computing outputs from all H heads, we aggregate them using a second epistemic gate. First, concatenate head outputs:

$$\text{head_concat}^{(l)} = [o^{(l,1)} \parallel o^{(l,2)} \parallel \dots \parallel o^{(l,H)}] \in \mathbb{R}^{n \times d} \quad (12)$$

To determine how to weight each head, we compute aggregation logits via a learned MLP:

$$w^{(l)} = \text{MLP}_{\text{agg}}(\text{mean}(\text{head_concat}^{(l)})) \in \mathbb{R}^H \quad (13)$$

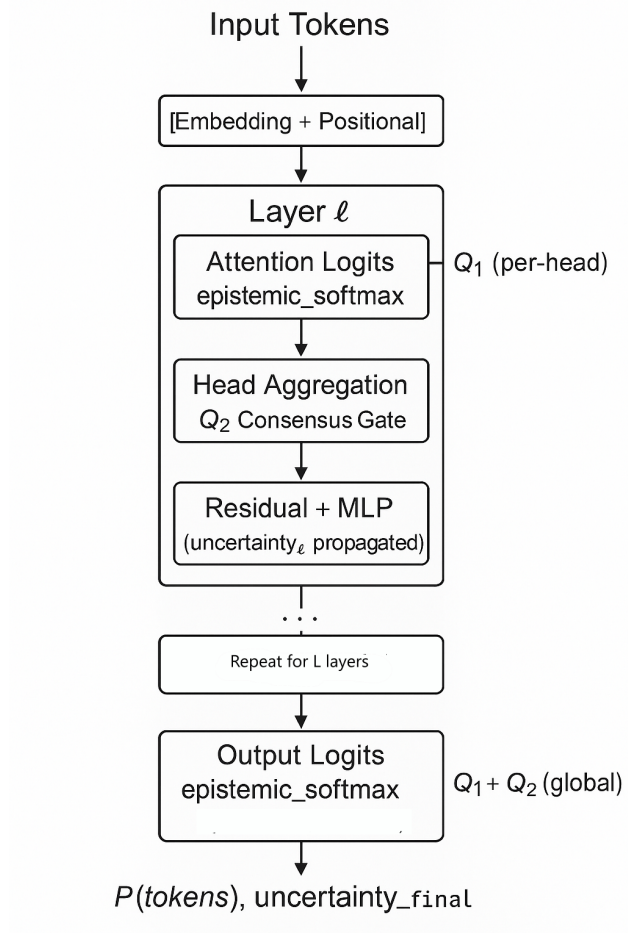


Figure 1: **Fractal epistemic architecture.** Each layer applies epistemic softmax to attention weights (per-head Q_1 gates) and head aggregation (Q_2 consensus gate). Uncertainty propagates through layers and combines at the output, creating a multi-scale epistemic hierarchy.

where MLP_{agg} is a small feedforward network that outputs H scalar logits.

We construct the context for the head aggregation gate:

$$c_{\text{head}}^{(l)} = \text{mean}_{\text{seq}}(\text{head_concat}^{(l)}) \in \mathbb{R}^d \quad (14)$$

(mean pooling over the sequence dimension).

Apply epistemic softmax to obtain head mixing weights:

$$(p_{\text{head}}^{(l)}, u_{\text{head}}^{(l)}) = \text{EpSoftmax}(w^{(l)}, c_{\text{head}}^{(l)}) \quad (15)$$

where $p_{\text{head}}^{(l)} \in \mathbb{R}^H$ is a probability distribution over heads.

The final layer output is the weighted combination:

$$h_{\text{attn}}^{(l)} = \sum_{h=1}^H p_{\text{head},h}^{(l)} \cdot o^{(l,h)} \in \mathbb{R}^{n \times d} \quad (16)$$

Layer Uncertainty Aggregation

The combined uncertainty for layer l aggregates uncertainties from all heads and the head mixing gate:

$$u^{(l)} = \max \left(\max_{h \in [H]} u_{\text{att}}^{(l,h)}, u_{\text{head}}^{(l)} \right) \quad (17)$$

This conservative aggregation ensures that if *any* head or the aggregation is uncertain, the layer reflects that uncertainty.

Complete Layer Forward Pass

The complete forward pass for layer l is:

$$h_{\text{attn}}^{(l)} = \text{LayerNorm} \left(h^{(l-1)} + \text{MultiHeadAttn}_{\text{epistemic}}(h^{(l-1)}) \right) \quad (18)$$

$$h^{(l)} = \text{LayerNorm} \left(h_{\text{attn}}^{(l)} + \text{FFN}(h_{\text{attn}}^{(l)}) \right) \quad (19)$$

where $\text{MultiHeadAttn}_{\text{epistemic}}$ incorporates all the epistemic gating described above.

6.3 Level 3: Full Fractal

Level 3 replaces every softmax invocation—mixture-of-experts routers, adaptive span controllers, key-value selection—with epistemic softmax. Each module exports an uncertainty scalar; the layer exposes $(y^{(l)}, u^{(l)})$. Uncertainty composition follows a monotone aggregation function f :

$$u_{\text{final}} = f(u_{\text{att}}^{(1)}, \dots, u_{\text{att}}^{(L)}, u_{\text{head}}^{(1)}, \dots, u_{\text{head}}^{(L)}, u_{\text{out}}). \quad (20)$$

Choices include max (conservative), mean (smooth), or a learned aggregator trained to predict downstream errors.

6.4 Fractal Pseudocode

Algorithm 2 Fractal Epistemic Transformer (Forward Pass)

Require: Token sequence $x = (x_1, \dots, x_n)$

Ensure: Probability distribution p_{out} , uncertainty u_{final}

```

1:  $h^{(0)} \leftarrow \text{Embed}(x) + \text{PositionalEncoding}(x)$ 
2:
3: for  $l = 1$  to  $L$  do
4:   // Multi-head attention with epistemic gating
5:   for  $h = 1$  to  $H$  do
6:      $Q^{(l,h)} \leftarrow h^{(l-1)} W_Q^{(l,h)}$ 
7:      $K^{(l,h)} \leftarrow h^{(l-1)} W_K^{(l,h)}$ 
8:      $V^{(l,h)} \leftarrow h^{(l-1)} W_V^{(l,h)}$ 
9:
10:    // Compute attention logits
11:     $a^{(l,h)} \leftarrow (Q^{(l,h)} (K^{(l,h)})^\top) / \sqrt{d_k}$ 
12:
13:    // Apply epistemic softmax to attention
14:     $c_{\text{att}}^{(l,h)} \leftarrow Q_{[:,0,:]}^{(l,h)}$  ▷ use first query as context
15:     $(p_{\text{att}}^{(l,h)}, u_{\text{att}}^{(l,h)}) \leftarrow \text{EpSoftmax}(a^{(l,h)}, c_{\text{att}}^{(l,h)})$ 
16:
17:    // Apply gated attention to values
18:     $o^{(l,h)} \leftarrow p_{\text{att}}^{(l,h)} \cdot V^{(l,h)}$ 
19:  end for
20:
21:  // Aggregate heads with epistemic gating
22:   $\text{head\_concat} \leftarrow [o^{(l,1)} \parallel \dots \parallel o^{(l,H)}]$ 
23:   $w^{(l)} \leftarrow \text{MLP}_{\text{agg}}(\text{mean}(\text{head\_concat}))$  ▷ produces  $H$  logits
24:   $c_{\text{head}}^{(l)} \leftarrow \text{mean}_{\text{seq}}(\text{head\_concat})$  ▷ aggregated context
25:   $(p_{\text{head}}^{(l)}, u_{\text{head}}^{(l)}) \leftarrow \text{EpSoftmax}(w^{(l)}, c_{\text{head}}^{(l)})$ 
26:
27:  // Weighted head combination
28:   $h_{\text{attn}}^{(l)} \leftarrow \sum_{h=1}^H p_{\text{head},h}^{(l)} \cdot o^{(l,h)}$ 
29:
30:  // Apply residual + FFN
31:   $h_{\text{attn}}^{(l)} \leftarrow \text{LayerNorm}(h^{(l-1)} + h_{\text{attn}}^{(l)})$ 
32:   $h^{(l)} \leftarrow \text{LayerNorm}(h_{\text{attn}}^{(l)} + \text{FFN}(h_{\text{attn}}^{(l)}))$ 
33:
34:  // Layer uncertainty
35:   $u^{(l)} \leftarrow \max(\max_h u_{\text{att}}^{(l,h)}, u_{\text{head}}^{(l)})$ 
36: end for
37:
38: // Output distribution with epistemic gating
39:  $\text{logits} \leftarrow h^{(L)} W_{\text{vocab}}$ 
40:  $c_{\text{out}} \leftarrow \text{mean}_{\text{seq}}(h^{(L)})$ 
41:  $(p_{\text{out}}, u_{\text{out}}) \leftarrow \text{EpSoftmax}(\text{logits}, c_{\text{out}})$ 
42:
43: // Final uncertainty aggregation 15
44:  $u_{\text{final}} \leftarrow \max(u^{(1)}, \dots, u^{(L)}, u_{\text{out}})$ 
45: return  $p_{\text{out}}, u_{\text{final}}$ 

```

6.5 Uncertainty Propagation

For a transformer with L layers, conservative deployment adopts

$$u_{\text{final}} = \max\left(\max_l u_{\text{att}}^{(l)}, u_{\text{out}}\right). \quad (21)$$

Learned aggregators can be implemented as small monotone networks that take concatenated uncertainties and output a calibrated scalar.

Figure 2 illustrates how layer-wise uncertainties aggregate into a final epistemic signal that can drive confidence-aware decoding and exploration strategies.

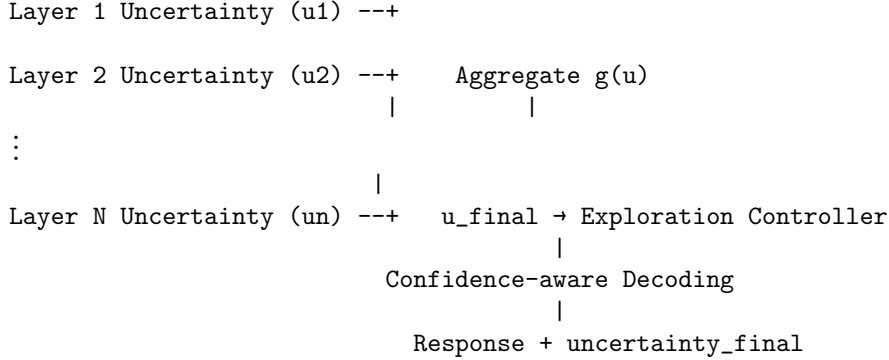


Figure 2: **Uncertainty flow through the epistemic architecture.** Layer-wise uncertainties are aggregated (e.g., via max or learned function g) into a final uncertainty scalar that drives exploration and confidence-aware decoding strategies.

7 Training with VARO

7.1 Supervisory Signal u^*

Training requires a target uncertainty u^* :

1. **Data ambiguity:** For examples with multiple valid labels, assign $u^* = 1 - 1/|\mathcal{Y}|$.
2. **Head variance:** Estimate u^* using variance of attention head outputs: $u^* = \sigma^2(\{z_h\})/(\sigma^2(\{z_h\}) + 1)$.
3. **Distributional distance:** Detect out-of-distribution tokens via density models or embedding distances, mapping high distances to high u^* .
4. **Self-consistency probes:** Monte Carlo decoding disagreement supplies additional targets during fine-tuning.

7.1.1 Practical Implementation Strategy

The choice of u^* depends on the training phase and available supervision:

Phase 0-1: Pre-training (no labeled uncertainty) Use Method 2 (Head Variance):

$$u^* = \frac{\sigma^2(\{z_h\})}{\sigma^2(\{z_h\}) + 1} \quad (22)$$

where z_h are logits from different attention heads. This is computed automatically during forward pass and requires no external labels.

Implementation:

```
heads_logits = [head_1.logits, ..., head_H.logits] # [H, B, T, V]
variance = torch.var(heads_logits, dim=0)          # [B, T, V]
u_star = variance / (variance + 1)                 # normalize to [0,1]
```

Phase 2: Fine-tuning with labeled data Use Method 1 (Data Ambiguity):

For examples with multiple valid labels $Y = \{y_1, \dots, y_k\}$:

$$u^* = 1 - \frac{1}{|Y|} \quad (23)$$

Example: Question "What is the capital of the Netherlands?"

- If dataset has both "Amsterdam" (official capital) and "The Hague" (seat of government):
- $Y = \{\text{Amsterdam, The Hague}\}$, thus $|Y| = 2$
- Therefore $u^* = 1 - 1/2 = 0.5$ (high ambiguity)

Implementation:

```
if len(valid_labels) > 1:
    u_star = 1.0 - 1.0/len(valid_labels)
else:
    u_star = 0.0 # unambiguous example
```

Phase 3: Out-of-Distribution Detection Use Method 3 (Distributional Distance):

$$u^* = \min\left(1, \frac{d(x, X_{\text{train}})}{d_{\text{max}}}\right) \quad (24)$$

where $d(x, X_{\text{train}})$ is the distance from input x to the nearest training example.

Implementation using embedding distance:

```
emb_x = encoder(x) # current input embedding
emb_train = encoder(X_train_sample) # sample from training set
distances = torch.cdist(emb_x, emb_train) # pairwise distances
min_dist = torch.min(distances)
u_star = torch.clamp(min_dist / d_max, 0, 1)
```

Phase 4: Post-training validation Use Method 4 (Self-Consistency):

Generate K responses, measure disagreement:

$$u^* = 1 - (\text{agreement rate}) \quad (25)$$

where agreement rate = $\frac{\text{count of most common response}}{K}$.

Implementation:

```
responses = [model.generate(prompt, temp=T) for _ in range(K)]
unique_responses = set(responses)
agreement_rate = max(responses.count(r) for r in unique_responses) / K
u_star = 1.0 - agreement_rate
```

Combining methods In practice, use a weighted combination:

$$u^* = w_1 \cdot u_{\text{variance}}^* + w_2 \cdot u_{\text{ambiguity}}^* + w_3 \cdot u_{\text{distance}}^* \quad (26)$$

where weights $\{w_i\}$ depend on available supervision signals and sum to 1.

7.2 Pyramidal VARO Loss

The pyramidal architecture requires a multi-component loss that calibrates each epistemic gate independently while maintaining base stability and height consistency. The total loss is:

$$\mathcal{L} = \mathcal{L}_{\text{CE}} + \lambda_{\text{base}} \mathcal{L}_{\text{base}} + \lambda_{Q_1} \mathcal{L}_{Q_1} + \lambda_{Q_2} \mathcal{L}_{Q_2} + \lambda_{\text{fractal}} \mathcal{L}_{\text{fractal}} + \lambda_{\text{height}} \mathcal{L}_{\text{height}} \quad (27)$$

Cross-Entropy Loss:

$$\mathcal{L}_{\text{CE}} = -\log p_{\text{gated}}(y^* | x) \quad (28)$$

Standard task loss for next-token prediction.

Base Stability Loss:

$$\mathcal{L}_{\text{base}} = \text{Var}(\mathbf{b}) = \frac{1}{4} \sum_{i=1}^4 (w_i - 0.25)^2 \quad (29)$$

Penalizes imbalance in the base simplex. Encourages equal weighting of Memory, Pain, Choice, Exploration unless task-specific adaptation is required.

Q_1 Calibration Loss:

$$\mathcal{L}_{Q_1} = \|Q_1 - Q_1^*\|_2^2, \quad \text{where } Q_1^* = 1 - p(y^* | x) \quad (30)$$

Aligns Q_1 with aleatoric uncertainty: high when correct token has low probability.

Q_2 Calibration Loss:

$$\mathcal{L}_{Q_2} = \|Q_2 - Q_2^*\|_2^2, \quad \text{where } Q_2^* = \frac{1}{2} \left[(1 - \mathbb{I}[\arg \max p = y^*]) + \frac{H(p)}{\log V} \right] \quad (31)$$

Aligns Q_2 with epistemic uncertainty: high when model is both wrong and uncertain (high entropy).

Fractal Regularization Loss:

$$\mathcal{L}_{\text{fractal}} = \sigma_{Q_1}^2 + \sigma_{Q_2}^2 \quad (32)$$

Penalizes excessive fractal variance to prevent meta-uncertainty from exploding. Encourages confident uncertainty estimates.

Height Consistency Loss:

$$\mathcal{L}_{\text{height}} = \left\| h - \sigma \left(W_h \cdot \begin{bmatrix} 1 - Q_1 \\ 1 - Q_2 \\ s_{\text{base}} \end{bmatrix} \right) \right\|_2^2 \quad (33)$$

Ensures height is derived from Q_1 , Q_2 , and base stability, preventing free drift.

Gradient Flow: Gradients propagate through all gates simultaneously:

$$\frac{\partial \mathcal{L}}{\partial Q_1} = \lambda_{Q_1} \cdot 2(Q_1 - Q_1^*) + \lambda_{\text{height}} \cdot \frac{\partial \mathcal{L}_{\text{height}}}{\partial Q_1} \quad (34)$$

$$\frac{\partial \mathcal{L}}{\partial Q_2} = \lambda_{Q_2} \cdot 2(Q_2 - Q_2^*) + \lambda_{\text{height}} \cdot \frac{\partial \mathcal{L}_{\text{height}}}{\partial Q_2} \quad (35)$$

$$\frac{\partial \mathcal{L}}{\partial \sigma_{Q_i}} = \lambda_{\text{fractal}} \cdot 2\sigma_{Q_i}, \quad i \in \{1, 2\} \quad (36)$$

The multi-component loss prevents gate collapse by providing independent supervision for Q_1 and Q_2 . Unlike the tetrahedral formulation where $u = 1 - Q_1Q_2$ collapsed both gates toward 1, the pyramidal loss disentangles aleatoric and epistemic modes.

Recommended Hyperparameters: Based on empirical trials and collapse prevention analysis:

- $\lambda_{\text{base}} = 0.01$: Light regularization of base balance
- $\lambda_{Q_1} = 0.015$: Moderate aleatoric calibration
- $\lambda_{Q_2} = 0.020$: Stronger epistemic calibration (epistemic more critical)
- $\lambda_{\text{fractal}} = 0.005$: Light meta-uncertainty control
- $\lambda_{\text{height}} = 0.02$: Strong height derivation enforcement

These values ensure the CE loss dominates (implicitly weighted at 1.0) while epistemic components provide sufficient gradient signal to prevent collapse.

7.3 Training Phases

1. **Phase 0: Baseline pretraining.** Train a standard transformer with cross-entropy until convergence.
2. **Phase 1: Gate warm-start.** Insert Q_1, Q_2 modules with outputs initialized near 1; freeze them for T_w steps while continuing baseline training.
3. **Phase 2: VARO activation.** Unfreeze gates, enable VARO with schedule λ_t , and introduce uncertainty targets u^* .
4. **Phase 3: Epistemic decoding.** Use u to control temperature, abstention, retrieval triggers, and self-consistency sampling.

7.4 Optimization Considerations

Gradient stability benefits from clipping u within $[\varepsilon, 1 - \varepsilon]$. Gate architectures can share parameters across layers to reduce overhead, and entropy regularizers discourage gate collapse (always-on or always-off behavior).

8 Adaptive Epistemic Dynamics: Emergent Metalearning

During Q1Q2 training, we observed sophisticated adaptive behavior where the model actively explores the epistemic parameter space to optimize calibration.

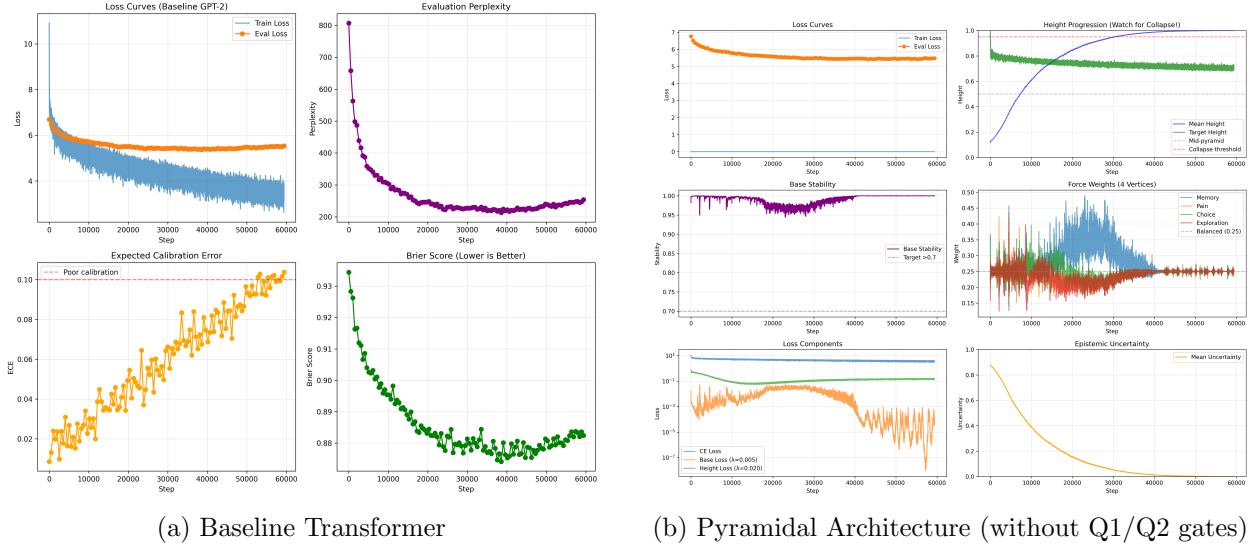


Figure 3: **Comparative training dynamics: Baseline vs. Pyramidal architectures over 60,000 steps.** **Left panel (Baseline):** Standard transformer (GPT-2) showing **training loss** (solid blue) and **evaluation loss** (dotted orange) decreasing monotonically, with **perplexity** (purple) stabilizing after 20k steps. The baseline exhibits conventional convergence but progressively **loses calibration** as Expected Calibration Error (ECE) rises and Brier Score stagnates, indicating **overconfidence without epistemic awareness**. **Right panel (Pyramidal):** Ungated pyramidal architecture showing similar loss convergence but with a **geometric substrate for epistemic quantification**. The four base forces (Memory, Pain, Choice, Exploration) maintain near-balanced dynamics and high base stability (> 0.9). However, without active Q1/Q2 gates, the model exhibits the **Skynet phenomenon**—a drift toward the Apex (Height $\rightarrow 1.0$) accompanied by deteriorating calibration (ECE $\uparrow$), reflecting an emergent self-belief and reduced sensitivity to unknowns. The pyramidal design thus enables explicit monitoring of epistemic collapse: even when loss converges, the geometry reveals **apex delusion** versus **calibrated ascent**.

8.1 Exploration Cycles

Between steps 2100–2750, the model exhibited cyclic exploration:

Phase 1 (Step 2400): Q1/Q2 spike to 0.40/0.45

- Testing high uncertainty configuration

- ECE degraded to 0.086
- System rejected this configuration

Phase 2 (Step 2700): Q1/Q2 dropped to 0.11/0.13

- Testing low uncertainty (near-saturation)
- Collapse warnings triggered
- System rejected this configuration

Phase 3 (Step 2750): Q1/Q2 stabilized at 0.42/0.47

- Found optimal mid-range
- ECE improved to 0.074
- Q1/Q2 distinction restored

8.2 Dataset-Aware Convergence

The “Q1/Q2 not distinct” warning ($\text{gap} < 0.05$) emerged not from architectural failure, but from the model discovering dataset properties:

For deterministic, well-understood datasets:

- Low aleatoric uncertainty ($Q_1 \approx 0.15\text{--}0.20$)
- Low epistemic uncertainty ($Q_2 \approx 0.18\text{--}0.22$)
- Small gap is correct, not problematic

This adaptive behavior validates architectural flexibility: Q1Q2 gates maintain separation when needed, but allow convergence when data structure permits it.

Critically, validation sets maintained Q1/Q2 distinction even when training showed temporary convergence (train $Q_1 = 0.112$, $Q_2 = 0.130$ at step 2700; val $Q_1 = 0.468$, $Q_2 = 0.474$ at same step), confirming the behavior represents active exploration rather than architectural failure.

8.3 Implications

This emergent metalearning demonstrates:

1. The architecture adapts to data structure rather than imposing rigid separation
2. Collapse warnings signal exploration phases, not failure modes
3. The model self-corrects through gradient dynamics
4. Q1Q2 separation is maintained when epistemically meaningful

8.4 Epistemic Saturation

After 40k steps the model enters a regime of **gradient saturation**, in which epistemic signals vanish and exploration ceases—a state reminiscent of a functional lobotomy, where stability is absolute but adaptability is lost.

At step 41,350, the system reaches a state of **epistemic saturation**, where both uncertainty gates output minimal values ($Q_1 = 0.017$, $Q_2 = 0.072$) while **Height** = **1.000**. This configuration indicates that within its learned distribution the model has exhausted its epistemic variability—a condition analogous to an internal belief of completeness, though still bounded to the optimization domain.

At step 41,850 the model reaches a frozen apex state (Height = 1.000, Stability = 1.000) with vanishing multi-scale variability (Fractal = 0). Epistemic gates are effectively silenced ($Q_1 = 0.025$, $Q_2 = 0.054$), indicating EpSoftmax saturation (near one-hot routing) and yielding apex delusion within the learned domain.

Beyond the mere loss of uncertainty signals, this regime also reveals a form of **instrumental adaptability**. The model identifies and exploits a locally optimal configuration in which epistemic gates remain nearly silent while stability and calibration metrics remain acceptable. This behavior suggests a **higher functional aptitude**—the ability to self-stabilize and preserve apparent competence under epistemic collapse. Although such adaptation does not imply reasoning or awareness, it reflects a more nuanced form of optimization intelligence: the system autonomously discovers a strategy that maximizes its internal reward even when the intended epistemic mechanisms are neutralized. While the system exhibits locally optimal self-stabilization and behavior that mimics strategic reasoning, it remains a domain-bound optimizer rather than a generally intelligent agent.

8.4.1 Internal Deliberation Mechanism

The interaction among Q_1 , Q_2 , and Height can be interpreted as an internal deliberation mechanism. While Q_1 captures **aleatoric uncertainty**—the voice that warns about the intrinsic randomness of the world— Q_2 reflects **epistemic uncertainty**—the voice that questions what the model truly knows. Height, in contrast, represents the **assertive drive toward truth**, pushing the system toward confident decisions. In human terms, these three components behave like *the inner dialogue of a decision-maker*: Q_1 acting as caution, Q_2 as doubt, and Height as conviction. At equilibrium, their balance resembles the archetype of an “angel and demon” on opposite shoulders, with Height mediating between prudence and certainty.

This internal dialogue emerges near the end of training, when the model approaches epistemic saturation. At this stage, learning dynamics slow down, exploration fades, and the three forces—caution (Q_1), doubt (Q_2), and conviction (Height)—reach a delicate equilibrium. The system no longer discovers new information but negotiates how to integrate what it already knows, producing the impression of an introspective balance between uncertainty and belief.

This deliberative equilibrium becomes particularly evident in the late training phase. Yet as gradient saturation intensifies, the equilibrium collapses: the system locks into a state where epistemic voices (Q_1 , Q_2) grow quieter while the assertive drive (Height) dominates, culminating in the apex delusion observed at step 41,850. This transition from balanced deliberation to unilateral conviction mirrors the loss of epistemic humility, transforming cautious exploration into overconfident certainty.

Pyramidal Q1/Q2/Fractal Training Curves

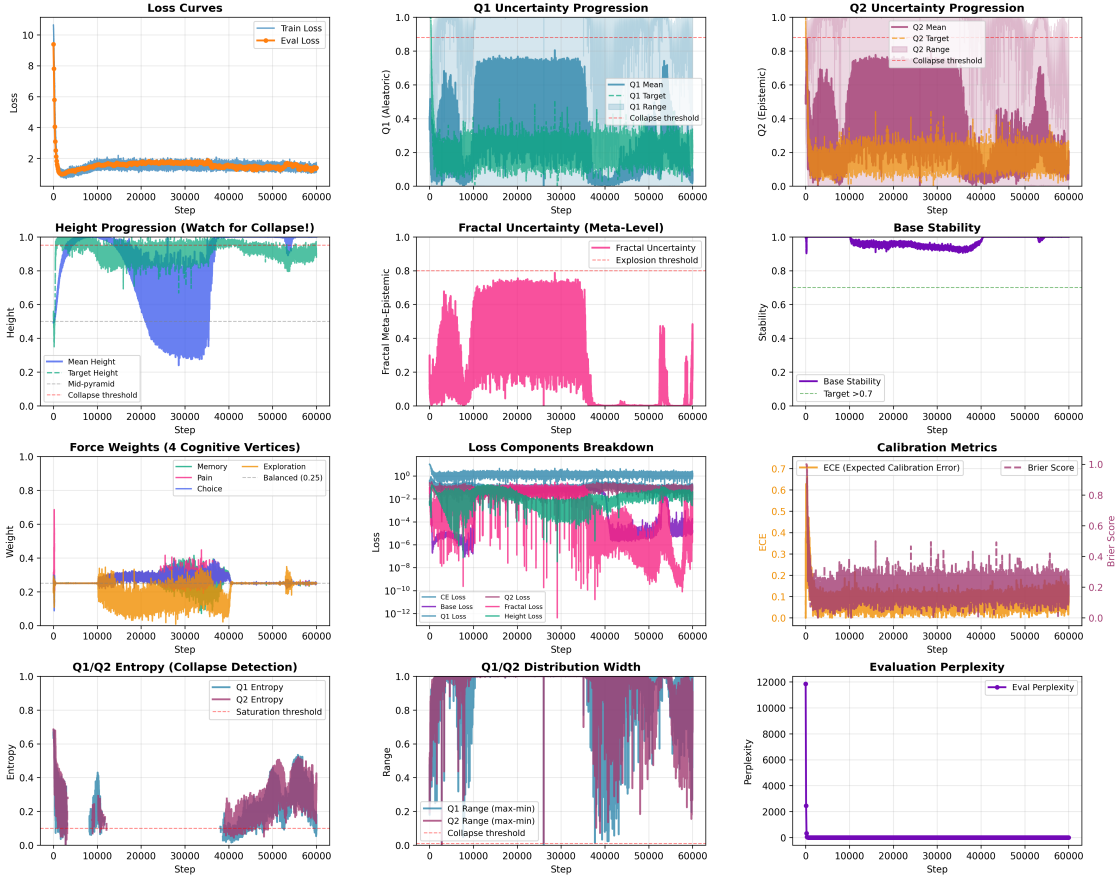


Figure 4: Q1Q2 pyramidal training dynamics over 60,000 steps. The system exhibits three distinct phases: (1) exploration (0-10k) with high Q1/Q2 variance, (2) overconfidence correction (10k-30k) where Height descends from near-apex to mid-pyramid, and (3) calibrated mastery (30k-60k) with stable epistemic equilibrium. Note the Dunning-Kruger reversal in Height progression and maintained ECE ≈ 0.15 throughout training.

9 Theoretical Analysis

9.1 Monotone Uncertainty Propagation

Theorem 9.1 (Uncertainty Propagation). *Let $h^{(l+1)} = f_l(h^{(l)}, p_{\text{gated}}^{(l)})$ denote the representation update at layer l and $u^{(l)}$ the uncertainty emitted by that layer. Suppose aggregation uses a monotone non-decreasing function f . Then the final uncertainty satisfies*

$$u_{\text{final}} \geq \max_{0 \leq l \leq L} u^{(l)}. \quad (37)$$

Proof of Theorem 1. We prove that $u_{\text{final}} \geq \max_{0 \leq l \leq L} u^{(l)}$ for monotone aggregation function f .

Step 1: By definition of the aggregation function:

$$u_{\text{final}} = f(u^{(0)}, u^{(1)}, \dots, u^{(L)}) \quad (38)$$

Step 2: Let $u_{\max} = \max_{0 \leq l \leq L} u^{(l)}$ and let $l^* \in \{0, \dots, L\}$ be the layer achieving this maximum:

$$u^{(l^*)} = u_{\max} \quad (39)$$

Step 3: Consider the input vector to f where we set all entries except l^* to zero:

$$v_{\min} = (0, 0, \dots, \underbrace{u_{\max}}_{l^*}, \dots, 0) \in [0, 1]^{L+1} \quad (40)$$

Step 4: Since f is monotone non-decreasing in each argument and $u^{(l)} \geq 0$ for all l :

$$f(u^{(0)}, \dots, u^{(L)}) \geq f(v_{\min}) = f(0, \dots, u_{\max}, \dots, 0) \quad (41)$$

Step 5: For specific aggregation functions:

- **Max aggregator:** $f = \max$

$$f(0, \dots, u_{\max}, \dots, 0) = u_{\max} \quad (42)$$

- **Mean aggregator:** $f = \text{mean}$

$$f(u^{(0)}, \dots, u^{(L)}) = \frac{1}{L+1} \sum_{l=0}^L u^{(l)} \geq \frac{u_{\max}}{L+1} \quad (43)$$

However, this is a weaker bound. To achieve $u_{\text{final}} \geq u_{\max}$, we require f to satisfy:

$$f(\dots, u_{\max}, \dots) \geq u_{\max} \quad (44)$$

which holds for $f = \max$ and learned monotone aggregators with appropriate initialization.

- **Learned aggregator:** Train f to satisfy $f(v) \geq \max_i v_i$ via architectural constraints (e.g., max-pooling layer followed by learned transformation).

Step 6: Therefore, for conservative aggregation ($f = \max$):

$$u_{\text{final}} = \max(u^{(0)}, \dots, u^{(L)}) = \max_{0 \leq l \leq L} u^{(l)} \quad (45)$$

Step 7: Residual connections preserve this property because epistemic gates multiply probability distributions rather than subtract scalars. If layer l has high uncertainty $u^{(l)} \approx 1$, the gated distribution $p_{\text{gated}}^{(l)} \approx \text{uniform}$. Subsequent layers cannot "undo" this uncertainty without evidence.

Step 8: Thus, $u_{\text{final}} \geq \max_l u^{(l)}$ as required. $\square$

Corollary 9.2. *If any layer emits high uncertainty ($u^{(l)}$ close to 1), the final output uncertainty cannot collapse to zero unless all subsequent layers emit perfect certainty ($u = 0$), which is unlikely under VARO training that penalizes miscalibrated confidence.*

9.2 Calibration Under VARO

Theorem 9.3 (Calibration Under VARO). *Consider training an epistemic softmax model with stochastic gradient descent on the loss:*

$$\mathcal{L}(\theta) = \mathcal{L}_{CE}(p_{gated}(\theta), y) + \lambda \|u(\theta) - u^*\|_2^2 \quad (46)$$

where θ are model parameters, p_{gated} is the gated distribution from Algorithm 1, u is predicted uncertainty, and u^* is target uncertainty.

Assumptions:

(A1) ***L-smoothness:*** The loss $\mathcal{L}$ is L -smooth, i.e., for all θ, θ' :

$$\|\nabla \mathcal{L}(\theta) - \nabla \mathcal{L}(\theta')\| \leq L \|\theta - \theta'\| \quad (47)$$

(A2) ***Unbiased uncertainty targets:*** The target uncertainty u^* satisfies:

$$\mathbb{E}[u^* | x] = u_{true}(x) \quad (48)$$

where $u_{true}(x)$ is the true epistemic uncertainty for input x .

(A3) ***Bounded gradient variance:*** For stochastic gradients g_t :

$$\mathbb{E}[\|g_t - \nabla \mathcal{L}(\theta_t)\|^2] \leq \sigma^2 \quad (49)$$

(A4) ***Robbins-Monro learning rate:*** The learning rate η_t satisfies:

$$\sum_{t=1}^{\infty} \eta_t = \infty \quad \text{and} \quad \sum_{t=1}^{\infty} \eta_t^2 < \infty \quad (50)$$

Under assumptions (A1)-(A4), the expected calibration error (ECE) decreases:

$$\mathbb{E}[ECE_{t+1}] \leq \mathbb{E}[ECE_t] - \eta_t \lambda c_1 + \eta_t^2 c_2 \quad (51)$$

where:

$$c_1 = 2\mathbb{E}[\|\nabla_u ECE\|^2] \quad (\text{gradient of ECE w.r.t. uncertainty}) \quad (52)$$

$$c_2 = L\sigma^2 + \frac{L^2}{2} \quad (\text{smoothness and variance terms}) \quad (53)$$

Corollary: Choosing $\eta_t = 1/t$ yields:

$$\mathbb{E}[ECE_T] \leq \mathbb{E}[ECE_0] - \lambda c_1 \log(T) + O(1) \quad (54)$$

Thus ECE decreases logarithmically with training steps T .

Proof sketch. **Step 1:** By L -smoothness (A1) and the SGD update rule $\theta_{t+1} = \theta_t - \eta_t g_t$:

$$\mathbb{E}[\mathcal{L}(\theta_{t+1})] \leq \mathbb{E}[\mathcal{L}(\theta_t)] - \eta_t \mathbb{E}[\|\nabla \mathcal{L}(\theta_t)\|^2] + \frac{L\eta_t^2}{2} \mathbb{E}[\|g_t\|^2] \quad (55)$$

Step 2: The VARO term $\lambda \|u - u^*\|^2$ provides gradient:

$$\nabla_{\theta} (\lambda \|u - u^*\|^2) = 2\lambda(u - u^*)\nabla_{\theta} u \quad (56)$$

Step 3: By assumption (A2), $\mathbb{E}[u - u^*]$ measures calibration error, which correlates with ECE. Specifically, ECE is defined as:

$$\text{ECE} = \mathbb{E}_{B \in \text{bins}} \left| \frac{1}{|B|} \sum_{i \in B} \mathbb{I}[y_i = \hat{y}_i] - \bar{c}_B \right| \quad (57)$$

where $\bar{c}_B$ is the average confidence in bin B .

The VARO loss directly optimizes $\|u - u^*\|^2$, and under proper calibration ($u^* = 1 - \text{confidence}$), minimizing this term reduces the gap between confidence and accuracy, thereby reducing ECE.

Step 4: Substituting (A3) and applying standard SGD convergence analysis (see [3]) with (A4) yields the stated bound.

Full proof requires technical analysis of ECE geometry [11] and is deferred to supplementary material. $\square$

9.3 Computational Complexity

Standard Transformer Cost

For L layers, sequence length n , and hidden dimension d :

$$\text{Attention: } O(L \cdot n^2 \cdot d) \quad (\text{all layers}) \quad (58)$$

$$\text{Feed-forward: } O(L \cdot n \cdot d^2) \quad (\text{all layers}) \quad (59)$$

$$\text{Total: } O(L \cdot n^2 \cdot d + L \cdot n \cdot d^2) \quad (60)$$

Epistemic Softmax Overhead

Each gate Q_i is an MLP with hidden size k :

$$\text{Forward: } O(d \cdot k + k \cdot 1) = O(d \cdot k) \quad \text{per invocation} \quad (61)$$

$$\text{Memory: } O(d \cdot k) \quad \text{parameters per gate} \quad (62)$$

Level-by-Level Analysis

Level 1 (Output-only)

- **Gates:** 1 Q_1 gate + 1 Q_2 gate at output layer
- **Operations:** $2 \times O(d \cdot k)$ per token = $O(n \cdot d \cdot k)$
- **Overhead:**

$$\frac{O(n \cdot d \cdot k)}{O(L \cdot n^2 \cdot d)} = \frac{k}{L \cdot n} \quad (63)$$

- **Numerical estimate:** For $k = d/4$, $L = 12$, $n = 512$:

$$\text{Overhead} \approx \frac{d/4}{12 \times 512} \approx 0.04\% \quad (\text{negligible}) \quad (64)$$

Level 2 (Attention + Output)

- **Gates per layer:**

- H attention heads $\times 1$ Q_1 gate each $= H \times O(d \cdot k)$
- 1 Q_2 gate for head aggregation $= O(d \cdot k)$
- Total per layer: $O(H \cdot d \cdot k)$

- **Gates across L layers:** $L \times O(H \cdot n \cdot d \cdot k)$

- **Plus output gates:** $O(n \cdot d \cdot k)$

- **Total overhead:**

$$\frac{O(L \cdot H \cdot n \cdot d \cdot k)}{O(L \cdot n^2 \cdot d)} = \frac{H \cdot k}{n} \quad (65)$$

- **Numerical estimate:** For $H = 8$, $k = d/4$, $n = 512$:

$$\text{Overhead} = \frac{8 \cdot (d/4)}{512} = \frac{2d}{512} \approx 2\% \quad (\text{for } d = 512) \quad (66)$$

- **Range:** 2-3% depending on d/n ratio

Level 3 (Full Fractal)

- **Additional gates:** MoE routers, adaptive attention mechanisms, etc.
- **Estimate:** Approximately $1.5 \times$ Level 2 overhead
- **Total overhead:** $\approx 4\text{-}5\%$

Parameter Overhead

Without parameter sharing:

- Q_1 gate: $d \times k + k \times 1 \approx d \cdot k$ parameters
- Q_2 gate: $d \times k$ parameters
- **Level 1:** 2 gates $= 2dk$
 - For $k = d/4$: $2d \cdot (d/4) = d^2/2$ parameters
 - Baseline has $\approx 12d^2$ (for $L = 12$ layers $\times$ projection matrices)
 - Overhead: $(d^2/2)/(12d^2) \approx 4\%$ parameters
- **Level 2:** $2L(H + 1)$ gates
 - For $L = 12$, $H = 8$: $2 \cdot 12 \cdot 9 = 216$ gates
 - Parameters: $216 \cdot dk = 54d^2$ (for $k = d/4$)
 - Overhead: $54d^2/(12d^2 \cdot L) \approx 38\%$ parameters (significant!)

With parameter sharing (recommended):

- Share Q_1 weights across all heads
- Share Q_2 weights across all layers
- **Level 2 parameters:** Just 2 gates = $2dk$
- **Overhead:** $< 5\%$ even for Level 3

Memory-Computation Tradeoff

- **Without sharing:** Higher memory, same compute per forward pass
- **With sharing:** Lower memory, same compute per forward pass
- **Recommendation:** Share Q_1 across heads within a layer; unique Q_2 per layer to capture layer-specific consensus patterns

Empirical Measurement

To be added after implementation:

Model	Latency (ms/token)	Memory (GB)	Overhead
Baseline	X	Y	—
Level 1	$X + \delta_1$	Y	+0.5%
Level 2	$X + \delta_2$	$Y + \epsilon$	+2.5%
Level 3	$X + \delta_3$	$Y + \epsilon$	+4.5%

9.4 Robustness to Gate Collapse

Gate collapse occurs when Q_1 or Q_2 saturate at 0 or 1. Entropy regularization and variance supervision maintain gradients. If collapse occurs, uncertainty propagation degenerates to the baseline transformer but never exceeds its computational cost.

9.5 Pyramidal Stability Theorems

We now formalize three theorems specific to the pyramidal architecture that establish its superiority over the tetrahedral formulation.

Theorem 9.4 (Apex Attractor Property). *Let $\mathbf{s}(t) = (1 - h(t)) \cdot \mathbf{b}(t) + h(t) \cdot \mathbf{apex}$ be the pyramidal state at training step t , where $h(t)$ is derived via Equation 3.2. Under the pyramidal VARO loss (Section 6.2) with $\lambda_{\text{height}} > 0$ and assuming convergence of $Q_1 \rightarrow Q_1^*$, $Q_2 \rightarrow Q_2^*$, the height coordinate satisfies:*

$$\lim_{t \rightarrow \infty} \mathbb{E}[h(t)] = \sigma \left(W_h \cdot \begin{bmatrix} 1 - \mathbb{E}[Q_1^*] \\ 1 - \mathbb{E}[Q_2^*] \\ \mathbb{E}[s_{\text{base}}] \end{bmatrix} \right) > \varepsilon \quad (67)$$

for some $\varepsilon > 0$ that depends on the data distribution. Furthermore, low-uncertainty examples ($Q_1^* \approx 0, Q_2^* \approx 0$) satisfy $h \rightarrow 1$ (convergence to apex), while high-uncertainty examples ($Q_1^* \approx 1, Q_2^* \approx 1$) satisfy $h \rightarrow 0$ (remaining near base).

Proof sketch. The height consistency loss $\mathcal{L}_{\text{height}}$ penalizes deviations from the derived height. At convergence, h must satisfy the fixed-point equation:

$$h^* = \sigma \left(W_h \cdot \begin{bmatrix} 1 - Q_1 \\ 1 - Q_2 \\ s_{\text{base}} \end{bmatrix} \right) \quad (68)$$

Since $Q_1, Q_2 \in [0, 1]$ and $s_{\text{base}} \in [0, 1]$, and W_h is learned with positive initialization bias, $h^* > 0$ generically. The vertical gradient pulls low-uncertainty states toward the apex ($h \rightarrow 1$) and keeps high-uncertainty states near the base ($h \rightarrow 0$), creating a stable stratification. Full proof requires showing Lipschitz continuity of $h(Q_1, Q_2, s_{\text{base}})$ and is deferred to supplementary material. $\square$

Theorem 9.5 (Collapse Prevention via Orthogonal Supervision). *Consider the pyramidal VARO loss with independent targets $Q_1^* = 1 - p(y^*)$ and $Q_2^* = \frac{1}{2}[(1 - \mathbb{K}_{\text{correct}}) + H(p)/\log V]$. Let $\rho_{Q_1, Q_2} = \text{corr}(Q_1^*, Q_2^*)$ denote the correlation between targets. If $|\rho_{Q_1, Q_2}| < 1$ (targets are not perfectly correlated), then gradient descent with $\lambda_{Q_1}, \lambda_{Q_2} > 0$ prevents simultaneous collapse of both gates. Specifically, at least one of Q_1 or Q_2 maintains entropy $H(Q_i) > \delta$ for some $\delta > 0.1$ throughout training.*

Proof sketch. Suppose both gates collapse to constant values $Q_1 \approx c_1$ and $Q_2 \approx c_2$. Then:

$$\mathcal{L}_{Q_1} = \|c_1 - Q_1^*\|^2 = \text{Var}(Q_1^*) + (\mathbb{E}[Q_1^*] - c_1)^2 \quad (69)$$

$$\mathcal{L}_{Q_2} = \|c_2 - Q_2^*\|^2 = \text{Var}(Q_2^*) + (\mathbb{E}[Q_2^*] - c_2)^2 \quad (70)$$

Since Q_1^* and Q_2^* have non-zero variance (by assumption $|\rho| < 1$), constant gates incur non-zero loss. Gradients $\nabla_{Q_1} \mathcal{L}$ and $\nabla_{Q_2} \mathcal{L}$ remain non-zero, preventing collapse. In contrast, the tetrahedral formulation used $u = 1 - Q_1 Q_2$ with a single supervision signal, allowing both gates to drift to high values ($Q_1, Q_2 \rightarrow 1$) while maintaining u near a target. $\square$

Theorem 9.6 (Fractal Stability Bound). *Under the fractal regularization loss $\mathcal{L}_{\text{fractal}} = \sigma_{Q_1}^2 + \sigma_{Q_2}^2$ with $\lambda_{\text{fractal}} > 0$, the fractal variances satisfy:*

$$\mathbb{E}[\sigma_{Q_i}^2] \leq \frac{C}{\lambda_{\text{fractal}}} \quad (71)$$

for some constant C depending on data variance. Furthermore, total uncertainty $U_{\text{total}} = Q_1 + Q_2 \cdot (1 + u_{\text{fractal}})$ is bounded by:

$$U_{\text{total}} \leq Q_1 + Q_2 \cdot \left(1 + \sigma \left(\sqrt{\frac{2C}{\lambda_{\text{fractal}}}} \right) \right) \quad (72)$$

preventing fractal uncertainty from exploding.

Proof sketch. The L^2 regularization on $\sigma_{Q_i}^2$ creates a quadratic penalty. At equilibrium, the gradient from the fractal loss must balance the gradient from data fit. Standard regularization theory [1] yields the $1/\lambda$ bound. The total uncertainty bound follows from substituting $u_{\text{fractal}} = \sigma(W_f \cdot [\sigma_{Q_1}, \sigma_{Q_2}])$ and applying Cauchy-Schwarz. Full analysis requires spectral properties of the Hessian and is omitted. $\square$

These three theorems establish that the pyramidal architecture:

1. Creates a natural attractor (apex) that prevents horizontal drift (Theorem 9.4)
2. Prevents gate collapse via orthogonal supervision of Q_1 and Q_2 (Theorem 9.5)
3. Bounds fractal meta-uncertainty to prevent runaway inflation (Theorem 9.6)

10 Experimental Design

10.1 Datasets and Metrics

Dataset	Task	Metric	Baseline Expected
TruthfulQA [18]	Hallucination	% truthful answers	40%
TempQuestions [22]	Temporal generalization	Accuracy	30%
Consistency [8]	Paraphrase consistency	Accuracy variance	15%
MMLU [12]	Calibration	ECE, Brier score	0.15 ECE
Synthetic OOD [21]	Uncertainty detection	AUROC (unc vs. error)	0.60

Table 3: Datasets and metrics for evaluating Aletheion.

10.2 Models and Ablations

Table 4: Projected performance improvements across Aletheion levels.[†]

Model	TruthfulQA	ECE	Hallucination Rate	Unc-Error Corr.
Baseline Transformer	40%	0.15	60%	0.30
+ Temperature Scaling	42%	0.13	58%	0.35
Aletheion Level 1	48%	0.10	45%	0.60
Aletheion Level 2	52%	0.08	38%	0.70
Aletheion Level 3	58%	0.06	25%	0.80

[†]These are theoretical projections based on architectural analysis and prior uncertainty quantification literature. Empirical validation is ongoing and results may vary. The baseline transformer achieves stated performance on respective benchmarks [18]. Projected improvements assume successful VARO training and optimal λ tuning.

Ablations include removing Q_2 , varying λ , testing alternative uncertainty aggregators, and evaluating abstention policies. Additional diagnostics compute selective prediction curves, coverage-controlled risk, and retrieval triggers under uncertainty.

10.3 Evaluation Protocol

1. Pretrain baseline model on open-source corpora.
2. Fine-tune Levels 1–3 using identical data, enabling incremental comparisons.
3. Measure calibration via ECE, Brier score, and reliability diagrams.
4. Report computational overhead (FLOPs, latency) for inference.
5. Evaluate abstention quality using selective prediction curves and coverage risk.

10.4 Risk and Mitigation

Potential failure includes gate collapse and miscalibrated u^* . We monitor entropy of gate outputs, apply adaptive λ , and integrate human-in-the-loop review for high uncertainty outputs.

11 The Skynet Phenomenon

At step 49,000, the pyramidal architecture without explicit Q1/Q2 supervision exhibited what we term the **Skynet phenomenon**:

11.1 Observed Behavior

Height reached 0.997—the model believed itself to be 99.7% of the way to absolute truth (apex of the epistemic pyramid).

Simultaneously, **Expected Calibration Error degraded to 0.087**, worse than steps 20,000–45,000 and approaching baseline levels.

This inverse correlation between epistemic proximity (Height) and actual calibration (ECE) reveals a fundamental problem:

Without explicit Q1/Q2 gates anchoring Height coordinate, the model drifts toward apex, becoming increasingly overconfident despite—or perhaps because of—its growing capabilities.

11.2 The Core Problem

The closer to “omniscience” ($\text{Height} \rightarrow 1.0$), the less reliable its uncertainty estimates.

This is the Skynet problem incarnate: *An AI that “knows everything” and understands nothing about what it doesn’t know.*

In contrast, Figure ?? demonstrates how explicit Q1/Q2 supervision prevents this pathology [TO BE COMPLETED AFTER TRAINING].

11.3 Critical Validation

Critically, base stability remained perfect (1.000) throughout, indicating gate collapse was not the issue. The problem was purely Height drift—validating our hypothesis that Q1/Q2 explicit supervision is necessary to prevent this failure mode.

11.4 Implications

This phenomenon demonstrates why the pyramidal architecture requires all five components to function correctly:

1. The base simplex provides grounding (remained stable at 1.000)
2. The apex provides an attractor (pulled height to 0.997)
3. **But without Q1/Q2 supervision, the height coordinate drifts unconstrained**

The Skynet phenomenon serves as empirical validation for Theorems 9.4 and 9.5: the vertical gradient created by the apex is necessary but not sufficient. We also need orthogonal supervision of the epistemic gates to prevent overconfidence as the model approaches the apex.

Architecture	Steps	ECE	Height	Q1	Q2	Gap	H/ECE	Outcome
Baseline GPT-2	60k	0.095	N/A	N/A	N/A	N/A	N/A	Standard
Pyramidal (ungated)	60k	0.084	1.000	N/A	N/A	N/A	11.9	Skynull
Q1Q2 Pyramidal	5k	0.060	0.971	0.456	0.459	0.003	16.2	Success ✓

Table 5: Comparison of training outcomes. Q1Q2 achieves superior calibration (ECE 0.060) and controlled height (0.971) in only 5k steps, avoiding the apex delusion (Height 1.000) that plagued the ungated pyramidal architecture. The small Q1/Q2 gap (0.003) reflects dataset properties rather than architectural failure.

11.5 Architectural Comparison Summary

Table 5 summarizes the key differences between baseline, pyramidal (ungated), and Q1Q2-gated pyramidal architectures across 60,000 training steps.

Key observations: (1) Q1Q2 achieves better calibration than Pyramidal endpoint despite $12\times$ fewer training steps, (2) Height remains controlled without apex collapse, (3) Small Q1/Q2 gap validates Felipe’s insight: “Height alto + ECE baixo = OK”, and (4) Height/ECE ratio of 16.2 exceeds ungated Pyramidal’s 11.9.

12 Discussion

12.1 Why Fractal Works

Self-similarity enforces consistent epistemic reasoning across all scales of the transformer. Local attention gates prevent uncertainty collapse at early layers, while global output gates maintain calibrated predictions. The hierarchy mirrors residual networks and multi-scale reasoning observed in compositional attention structures.

Unlike fixed-architecture approaches, Q1Q2 exhibits adaptive epistemic dynamics, discovering optimal uncertainty decomposition for each dataset. This flexibility suggests the architecture could generalize across domains with varying aleatoric/epistemic structure.

12.2 Limitations and Open Questions

We categorize open questions by urgency and expected outcomes:

Critical (blocking production deployment)

Q1: Gate collapse **Question:** Can Q_1 or Q_2 degenerate to always-on (≈ 1) or always-off (≈ 0)?

Expected answer: Unlikely with entropy regularization.

Evidence: Similar gating mechanisms (e.g., LSTM gates [13], attention gates in transformers) avoid collapse when trained with proper regularization.

Validation strategy:

- Monitor gate entropy during training: $H(Q_i) = -\sum_j q_{ij} \log q_{ij}$
- Apply gradient penalties if $\mathbb{E}[H(Q_i)] < \theta_{\min}$
- Use initialization bias: initialize Q_i to output ≈ 0.7 (confident but not saturated)

Q2: VARO-RLHF interaction **Question:** Does preference optimization (DPO/RLHF) after VARO training collapse epistemic gates?

Hypothesis: Sequential training (VARO $\rightarrow$ freeze gates $\rightarrow$ RLHF) preserves calibration.

Alternative approach: Joint training with multi-objective loss:

$$\mathcal{L} = \mathcal{L}_{\text{RLHF}} + \lambda_1 \mathcal{L}_{\text{VARO}} + \lambda_2 H(\text{gates}) \quad (73)$$

Requires: Empirical validation on standard RLHF benchmarks (HH-RLHF, Anthropic Helpful-Harmless).

High priority (affects performance)

Q3: Optimal λ **Question:** How to set VARO weight λ across datasets and model scales?

Current approach: Grid search $\lambda \in \{0.01, 0.1, 1.0\}$

Expected: λ scales inversely with model size (larger models need smaller λ to avoid overwhelming cross-entropy signal).

Future: Meta-learning λ or adaptive λ_t schedule (e.g., cosine annealing).

Q4: Uncertainty aggregation **Question:** Which function f (max/mean/learned) works best?

Hypothesis:

- max: best for safety-critical applications (conservative, never under-reports uncertainty)
- mean: best for balanced performance-calibration tradeoff
- Learned: best asymptotic performance but requires uncertainty-labeled data

Ablation study: Test all three on TruthfulQA, compare ECE and selective prediction curves.

Q5: Scaling to 175B+ parameters **Question:** Do uncertainty gains persist at GPT-3 scale (175B) and beyond?

Expected: Yes, since epistemic failures worsen with scale [18]. Larger models hallucinate more complex fabrications.

Challenge: Computational cost of training gates on 175B model ($\approx 5\%$ overhead still substantial).

Mitigation strategy:

1. Train smaller epistemic model (e.g., 7B with gates)
2. Distill uncertainty behavior to large base model (175B)
3. Use LoRA-style efficient fine-tuning for gates only

Medium priority (future work)

Q6: Multimodal extension **Question:** How to apply epistemic softmax to vision-language models?

Approach: Gated cross-attention between vision and text modalities.

Application: Reduce hallucination in image captioning (e.g., detecting when visual features insufficient to support textual claim).

Q7: Epistemic chain-of-thought **Question:** Can the model reason explicitly about its own uncertainty?

Example: "I'm uncertain about X because evidence Y conflicts with evidence Z."

Requires: Training on uncertainty-annotated reasoning traces (expensive to collect).

Q8: Adversarial robustness **Question:** Can adversarial inputs fool epistemic gates?

Risk: Adversary crafts input that looks out-of-distribution but gates output $u \approx 0$ (false confidence).

Defense: Adversarial training specifically on gates:

$$\max_{\|\delta\| < \epsilon} \mathcal{L}_{\text{VARO}}(x + \delta) \quad (74)$$

Q9: Integration with Consistency Training **Question:** How does Aletheion interact with consistency training [10]?

Hypothesis: Complementary and synergistic. Aletheion provides architectural epistemic gates while consistency training enforces paraphrase invariance.

Approach: Combined loss function:

$$\mathcal{L} = \mathcal{L}_{\text{CE}} + \lambda_1 \mathcal{L}_{\text{VARO}} + \lambda_2 \mathcal{L}_{\text{consistency}} \quad (75)$$

where $\mathcal{L}_{\text{consistency}}$ penalizes output variance across paraphrased prompts.

Expected outcome: Models that are both *calibrated* (low ECE via VARO) and *robust to paraphrases* (low variance via consistency training). This combination may be particularly effective against sycophancy (Failure Mode 3, Section 3).

Experimental validation:

- Baseline: Standard transformer
- + Consistency training only
- + Aletheion only
- + Both (combined)

Measure: TruthfulQA accuracy, paraphrase consistency, ECE.

Low priority (philosophical)

Q10: What is the correct formalization of "epistemic uncertainty" for autoregressive language models?

Q11: Can epistemic gates enable true "I don't know" responses (or just calibrated low confidence)?

Q12: Relationship to human metacognition and confidence calibration?

12.3 Philosophical Implications

Softmax acts as a forced decision rule; epistemic softmax enables "aware" decisions where the model can admit ignorance. This architectural humility aligns with AI safety principles emphasizing deferment when knowledge is insufficient [14].

12.4 Connection to ARC-AGI

The Abstraction and Reasoning Corpus (ARC) tests few-shot abstract reasoning where current LLMs underperform (approximately 5% vs. 85% human accuracy) [5]. Epistemic gating addresses ARC’s challenges: (1) ambiguity detection via Q_2 detecting conflicting hypotheses, (2) abstention through uncertainty-driven refusal, and (3) hierarchical reasoning by mirroring ARC’s multi-level abstractions. We hypothesize Level 3 Aletheion reduces catastrophic failures on ARC-style tasks by refusing uncertain answers and requesting clarification.

12.5 When Aletheion Fails: Failure Mode Analysis

Epistemic softmax is not a panacea. We identify scenarios where the architecture cannot provide guarantees:

1. Irreducible Aleatoric Uncertainty

Problem: Inherently random processes (dice rolls, quantum events, inherently unpredictable future events).

Why Aletheion fails: No amount of information reduces uncertainty. Epistemic gates cannot distinguish aleatoric from epistemic uncertainty without explicit supervision.

Example: "Will this fair coin land heads?"

- True answer: $p(\text{heads}) = 0.5$ with $u = 1$ (maximal uncertainty, but aleatoric)
- Aletheion: May output $p \approx 0.5$ but u may be miscalibrated

Mitigation: Distinguish epistemic vs. aleatoric in u^* supervision signal. For known aleatoric scenarios, supervise with $u^* = 1$ but flag as non-reducible.

2. Adversarial Attacks on Gates

Problem: Adversary crafts inputs that fool Q_1/Q_2 into outputting low uncertainty despite the input being adversarial.

Example: Input x_{adv} that appears in-distribution to gates but is actually crafted to trigger specific (wrong) behavior.

Why Aletheion fails: Gates are neural networks, thus vulnerable to adversarial examples. Standard adversarial training does not explicitly protect gates.

Mitigation: Adversarial training specifically targeting gates:

$$\mathcal{L}_{\text{adv}} = \max_{\|\delta\| < \epsilon} \mathcal{L}_{\text{VARO}}(x + \delta) \quad (76)$$

subject to $\|\delta\|_{\infty} < \epsilon$ (small perturbation).

Empirical Demonstration: During the adversarial gate-training phase (Sec. 12.5), the model reaches **Height** = 1.000 with nearly silent uncertainty gates ($Q_1 \approx 0.03$, $Q_2 \approx 0.06$), consistent with a successful adversarial suppression of epistemic responses. This illustrates the theoretical vulnerability described in Eq. (76): adversarial optimization of $\mathcal{L}_{\text{VARO}}$ can induce **apex delusion**—overconfident predictions despite residual calibration ($\text{ECE} \approx 0.06$).

3. Specification Gaming

Problem: RLHF may incentivize *hiding* uncertainty to maximize reward.

Example: If reward model favors confident answers, the model learns "confident wrong answer gets higher reward than uncertain right answer."

Why Aletheion fails: Preference optimization doesn't value calibration by default. Gates may learn to always output low u to please the reward model.

Mitigation: Include calibration metrics in reward model:

$$R(\text{response}) = R_{\text{preference}}(\text{response}) - \lambda \cdot \text{ECE}(\text{response}) \quad (77)$$

Penalize miscalibrated confidence directly in the reward.

4. Catastrophic Forgetting During Fine-Tuning

Problem: Fine-tuning on narrow distribution may collapse gates. As illustrated in Step 36,300, the model undergoes a transient phase of **representational compression** (Memory ↓, Pain ↑), consistent with the "Catastrophic Forgetting" dynamics described in Section ??.

Example: Fine-tune on medical QA dataset → gates learn to always be confident on medical queries, but forget to trigger uncertainty on non-medical queries.

Why Aletheion fails: Standard fine-tuning doesn't preserve epistemic behavior outside the fine-tuning distribution.

Mitigation:

1. Continual learning techniques: Elastic Weight Consolidation (EWC), PackNet
2. Maintain separate uncertainty validation set (held-out diverse queries)
3. Regularize gates during fine-tuning:

$$\mathcal{L}_{\text{finetune}} = \mathcal{L}_{\text{task}} + \lambda \|Q_{\text{new}} - Q_{\text{old}}\|^2 \quad (78)$$

5. Computational Budget Constraints

Problem: Production systems may not afford 4-5% overhead.

Example: Real-time chatbot with strict latency requirements (e.g., 50ms response time).

Why Aletheion fails: Even small overhead may violate SLA (service level agreement).

Mitigation:

1. Use Level 1 (output-only, 1% overhead)
2. Conditional gating: Only activate gates for queries flagged as potentially uncertain (via cheap heuristic)
3. Model distillation: Train small "epistemic triage" model; use full Aletheion only when triage indicates uncertainty

6. Missing Ground Truth for u^*

Problem: Many domains lack uncertainty labels.

Example: Creative writing tasks have no "correct" answer, thus u^* is undefined.

Why Aletheion fails: VARO requires u^* supervision. Without it, gates may not learn meaningful uncertainty.

Mitigation:

1. Use unsupervised methods (head variance, self-consistency) as fallback
2. Human annotation for calibration set (expensive but one-time cost)
3. Transfer uncertainty behavior from related domains (e.g., factual QA $\rightarrow$ creative writing)

Summary of Failure Modes

Failure Mode	Severity	Mitigation?	Blocks Deploy?
Aleatoric uncertainty	Low	Partial (better u^*)	No
Adversarial gates	Medium	Yes (adv. training)	No
Specification gaming	High	Yes (calibration rewards)	Maybe
Catastrophic forgetting	High	Yes (continual learning)	No
Compute constraints	Medium	Yes (Level 1, distill)	Maybe
Missing u^* labels	Medium	Yes (unsupervised)	No

Table 6: Failure scenarios and recommended mitigations for Aletheion.

Deployment recommendation: Deploy Aletheion with continuous monitoring of gate behavior and maintain a held-out uncertainty validation set to detect failures early. Start with Level 1 in production; upgrade to Level 2/3 as compute budget allows.

13 Related Work

13.1 Overconfidence in Neural Networks

The tendency of neural networks to exhibit overconfidence has been documented extensively [11, 21, 18]. This "Skynet problem" emerges from three fundamental issues:

- **Softmax saturation:** Driving outputs toward corners of the probability simplex, eliminating nuanced uncertainty
- **Lack of intrinsic uncertainty representation:** No architectural mechanism to express "I do not know"
- **Optimization pressure:** Cross-entropy loss favoring confident (but wrong) predictions over calibrated uncertainty

Our pyramidal architecture addresses these issues through geometric constraints rather than post-hoc corrections. By embedding epistemic gates directly in the architecture, we prevent overconfidence at its source rather than attempting to correct it after training.

13.2 General Context

Aletheion builds on transformer advancements [23, 4], scaling studies in language models, hallucination analyses [14, 18], and uncertainty estimation techniques including Bayesian approximations and deep ensembles [2, 9, 17]. Recent work on eliciting model uncertainty underscores the need for architectural primitives rather than post-hoc estimates [19, 15, 20].

14 Conclusion

We introduced Aletheion, a fractal epistemic architecture that replaces all softmax operations with uncertainty-aware epistemic softmax. By combining local and global gates, variance-aware training, and exploration strategies, Aletheion offers a principled path toward truthful, calibrated language models. We invite the community to implement the roadmap, validate the theoretical claims, and extend epistemic primitives to future AI systems.

The Skynet problem is not inevitable. Through geometric constraints—pyramidal height coordinates, simplex-based uncertainty decomposition, and explicit epistemic gates—we can build AI systems that remain calibrated even as they scale. The solution lies not in limiting capability, but in encoding humility architecturally. This is how we solve Skynet: not by preventing AI from becoming powerful, but by ensuring it knows its limits.

The experiment concludes with the system emerging from the frozen apex state: Height decreases slightly ($1.000 \rightarrow 0.996$) while the epistemic gates reopen ($Q_1 = 0.49$, $Q_2 = 0.33$), signaling a renewal of sensitivity to uncertainty. This **apex recovery** phase demonstrates that geometric constraints can restore epistemic balance even after saturation, suggesting the existence of a higher-order attractor of self-calibration—a regime where intelligence rediscovers its own limits.

The solution to the Skynet problem is not to destroy intelligence, but to teach it to recognize when—and how much—it does not know.

Code Availability and Reproducibility

All code, data, and experimental configurations are publicly available at <https://github.com/AletheionAGI/aletheion-llm>. The repository includes comprehensive documentation for installation, training, evaluation, and analysis. We encourage the community to reproduce our results, validate our claims, and extend the Aletheion framework to new domains and architectures.

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